A Simple Method for Operating the Delta Connection Standard of the 3-phase Induction Motor on Single Phase Supply

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Abstract—This research is purposed to establish a simple method for operating the three phase induction motors of delta connection standard with single-phase power by using capacitor circuit to the motor. The research was conducted at the Laboratory of the Electrical Engineering of Institut Teknologi Padang. The object used in this research was the 3-phase induction motor of 1.5 HP, 380/220V, Y/Δ, 2.75/4.74A, 4 poles, 50 Hz, 1400 RPM. The results showed that the motor could work well on single phase power load by up to 66% of the 3-phase rating. The motor could operate on power factor close to unity, with lower current harmonic distortion and efficiency 99.76%.

Keywords: Capacitor circuit, capacitance of the start and run capacitors, current flowing to the winding of the motor.

I. INTRODUCTION

The 3-phase induction motor is an electric motor which is widely used today, especially in the industrialized world since the motor is widely available with great power. This motor operates normally using the 3-phase power system. This motor has 3 coils identities are separated from each other across 120° electricity that powered by a 3-phase power system. They will produce a resultant magnetic flux that rotates like poles actual magnet spinning mechanism. In certain areas which are only available 1-phase power system, it is not possible to operate the motors on normal operation. Therefore, the motors are forced to operate on a 1-phase system.

In general, the 3-phase induction motor has two types connection coil for operating in normal operation, namely wye and delta connection system as shown in Fig. 1. To improve the starting torque and operating characteristics of the motors, they could be operated on a single phase supply as shown in Fig. 2 and Fig.3.

Figs. 2 and 3 show some methods for operating the induction motors on single phase power. Fig. 4 shows a method that used for operating the delta connection...
connection standard of the 3-phase induction motor on a single phase supply. Fig. 5 shows the control circuit used in the Fig. 4 for operating the motor on single phase supply.

Fig. 4 The method for operating the delta connection standard of the 3-phase induction motors on single-phase supply

\[
Z_b = \frac{V^2}{VA}
\]  

\( 'V' \) is a single phase voltage source \( (V_{LN}) \), ‘VA’ is apparent power of the 3-phase induction motor and ‘Zb’ is the base impedance of the motor. Furthermore, we will obtain the actual value of the capacitive reactance ‘Xc’ for the delta connection standard of the motor must be becomes \( ^5^7 \):

\[
X_c = (X_{C(Pu)})(Zb)
\]  

The value of the capacitance of start capacitor ‘Cs’ than can be obtained for delta connection standard of the motor by using the following equation.

\[
Cs = \frac{1}{\sqrt{3}(2.\pi.f.X_c)} \text{ (Farad)}
\]  

The equation (4) then can be rewritten as follows:

\[
Cs_\Delta = \frac{(0.11033)(I_p)}{(f)(V_{LN})} \text{ (Farad)}
\]

‘Cs_\Delta’ is the total capacitance of the start capacitor \( (Cs + Cr \text{ from fig. 4) } \), ‘Il’ is the line current standard of the motor (A), ‘f’ is the source frequency (Hz), \( V_{LN} \) is the amplitude of the single phase voltage source of line to neutral (Volt).

II. START CAPACITOR

Referring to Fig. 4 can be explained that the start capacitor ‘Cs’ and run capacitor ‘Cr’ accidentally placed in series with the coil R and S to create the highest torque of the motor. If referring to the theory of the ‘Torque start maximum per ampere’, the formula, then can be obtained as follow\(^5\):  

\[
X_{C(Pu)} = Xa + \frac{-XmRa + Zm\sqrt{Ra(Ra + Rm)}}{Rm}
\]

‘X_{C(Pu)}’ is the capacitive reactance of the start capacitor to be used (in Per-unit system, Pu), ‘Xa’ is the inductive reactance of the coil R and S (in Pu), Ra is the resistance of the coil R and S (in Pu), ‘Xm’ is the inductive reactance of the coil T (in Pu), ‘Rm’ is the resistance of the coil T (in Pu) and ‘Zm’ is the impedance of the coil T (in Pu). To obtain the true value of ‘Xc’, it must be sought from the base impedance values used in induction motor by using the following formula\(^7\):

\[
Zb = \frac{V^2}{VA}
\]  

The amount of reactive power (VARc) which donated the capacitor then can be written from equation (7) as\(^5\):  

\[
V_c = 2 \cdot V_{LN}
\]
\[ \text{VAR}_C = \omega C \left( \frac{V_C}{L} \right)^2 = 4 \omega C \left( \frac{V_{LN}}{L} \right)^2 \]  
(8)

C is referred to \( C_{r} \) from the Fig. 4. \( \text{VAR}_C \) will become apparent power of the 3-phase induction motor when operate on 1-phase power. If \( \text{VAR}_{3ph} \) is a reactive power while the motor operates at 3-phase supply, the amount of reactive power induction motor in a single phase supply (\( \text{VAR}_M \)) becomes\(^{5,7,11}\):

\[ \text{VAR}_M = \text{VAR}_{3ph} - \text{VAR}_C \]  
(9)

The magnitude of the line current (\( I_{L-1} \)), power factor (\( \cos \phi \)) and input power (\( P_L \)) of the motor in a single phase supply become\(^{5,7,11}\):

\[ I_{L-1} = \frac{\text{VAR}_C}{V_{LN}} \]  
(10)

\[ \sin \phi = \frac{\text{VAR}_M}{\text{VAR}_C} \]  
(11)

\[ \cos \phi = \cos(\sin^{-1} \phi) \]  
(12)

\[ P_L = \text{VAR}_C \cdot \cos \phi \]  
(13)

IV. TEST RESULT

The motor used in this research is the 3-phase induction motor of 1.5 HP, 380/220V, Y/\( \Delta \), 2.75/4.74 A, 4 poles, 50 Hz, 1400 RPM. The motor is operated in delta connection standard on 3-phase supply (from Fig.1b) and by using fig. 4 on single phase supply. Test result of this research about power factor, rotor speed of the motor, efficiency, and total current harmonic distortion are given in Figs 6, 7, 8 and 9 respectively. The control box of the motor with all components that used in this research is given in Fig. 10. The red lines in the Fig. 6 until Fig. 9 are the characteristics of the motor during operation on 3-phase system, while the black lines are during operation on a single phase system using a run capacitor 30 \( \mu \)F. From the figures can be seen that in general the motor can operate with better performance on single phase power compared to operating on three-phase power, but the output power of the motor (66% from the 3-phase rating). From the data in Fig. 6 until Fig. 9 show that with the same load conditions the motor can operate on single phase supply with higher power factor (close to unity), higher efficiency (99.759%) and lower harmonic distortion.

From the result of this research can be seen that the motor has better performance while operating on single phase supply.
From the research that has been done can be summarized as follows.

1. The method that used in this research could work well to operate the delta connection standard of the 3-phase induction motor on single-phase power at load up to 66% of its 3-phase nominal rating.
2. The method can operate the motor at a power factor close to unity, higher efficiency (99.759%) and lower harmonic distortion

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